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to provide a coherent way of dealing with the tuning of PID controllers. The particular method at the core of the book is the so-called model-reference robust tuning (MoReRT), developed by the authors. MoReRT constitutes a novel and powerful way of thinking of a robust design and taking into account the usual design trade-offs encountered

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Abstract. The aim of this paper is to present a robust tuning method for two-degree-of-freedom (2DoF) proportional integral derivative controllers with filter (PID 2F) for inverse response controlled processes modeled by a second-order plus a right-half plane zero (SOPRHPZ) transfer function. This is based on the use of a model-reference optimization procedure with servo and regulatory closed-loop transfer functions targets.

Robust tuning of 2DoF five-parameter PID controllers for ...
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